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## Non-linear programming

We start with systems in which the equations of constraint are linear. This condition will fit a large no. of problems of the chemical industry as we shall show later. We shall first solve a very simple problem in the geometric field. We minimize:

$$(1) \quad S = (x_1 - 2)^2 + (x_2 - 3)^2 + (x_3 - 5)^2 + 12$$

subject to the constraints:

$$(2) \quad 2x_1 + x_2 + x_3 = 12$$

$$(3) \quad 1x_1 + 2x_2 + 3x_3 = 26$$

$$x_1 > 0, x_2 > 0, x_3 > 0$$

Some point on the locus of the intersection of (2) and (3) will optimize (1).

the line of intersection of the two planes (2) and (3) has the

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direction  $(1-5+3)$ 

and a point on this line of intersection may be found by making say  $x_1 = 0$  and solving for  $x_2$  and  $x_3$ . Doing this we get

$$0 + x_2 + x_3 = 12$$

$$0 + 2x_2 + 3x_3 = 26 \quad \text{whence}$$

$$x_2 = 10, \quad x_3 = 2$$

the equation of this line may be written:

$$(4) \quad r = (0+10+2) + t(1-5+3) \quad \begin{pmatrix} t=0 \\ t=2 \end{pmatrix}$$

put (4) into (1) and we get

$$S = (t-2)^2 + (7-5t)^2 + (3t-3)^2 + 12$$

$$ds/dt = 0 = 2(t-2) - 10(7-5t) + 6(3t-3) \therefore$$

$$t = 92/70$$

$$r = (0+10+2) + (92/70)(1-5+3) = (92+240+416)/70$$

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$$S = (92/70 - 2)^2 + (7 - 92/14)^2 + (274/70)^2 + 12 = 1.54 + 12 = 13.543$$

This sphere represented by (1) simply expands or contracts till it just touches the line of intersection of (2) and (3) represented by (4). Note that in this case all the components of  $r$  are positive.

Again one may solve (2) and (3) for  $x_2$  and  $x_3$  in terms of  $x_1$ . Doing this we get:

$$x_2 = 10 - 5x_1 \quad \therefore$$

$$x_3 = 2 + 3x_1$$

$$S = (x_1 - 2)^2 + (7 - 5x_1)^2 + (3x_1 - 3)^2 + 12$$

$$\partial S / \partial x_1 = 0 = 2(x_1 - 2) - 10(7 - 5x_1) + 6(3x_1 - 3)$$

$$x_1 = 92/70 \quad x_2 = 24/7, \quad x_3 = 416/70$$

$$S = (92/70 - 2)^2 + (24/7 - 3)^2 + (416/70 - 5)^2 + 12 = 13.543$$

which is the same as before. Let us

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Change our objective function to

$$S = (x_1 + 2)^2 + (x_2 + 3)^2 + (x_3 + 5)^2 + 12$$

with the same constraints as before.

$$\begin{aligned} R &= (0 + 10 + 2) + t(1 - 5 + 3) \\ &= t + (10 - 5t) + (2 + 3t) \end{aligned} \quad \begin{pmatrix} t \geq 0 \\ t \leq 2 \end{pmatrix}$$

$$S = (t + 2)^2 + (10 - 5t)^2 + (3t + 2)^2 + 12$$

$$S' = 2(t + 2) - 10(10 - 5t) + 6(3t + 2) = 0$$

$$70t = 84 \therefore t = 1.2$$

$$R = 1.2 + 4 + 5.6$$

$$S = (3.2)^2 + (7)^2 + (10.6)^2 + 12 = 183.60 = \min$$

All the components of  $r$  are positive.

we change our objective function again:

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$$S = (x_1 + 2)^2 + (x_2 - 12)^2 + (x_3 + 5)^2 + 12$$

$$R = t + (10 - 5t) + (2 + 3t)$$

$$S = (t + 2)^2 + (-5t - 2)^2 + (3t + 7)^2 + 12$$

$$S = (t + 2)^2 + (5t + 2)^2 + (3t + 7)^2 + 12$$

$$S' = 2(t + 2) + 10(5t + 2) + 6(3t + 7) = 0$$

$$70t = -66 \quad \therefore t = -0.943$$

$$R = -0.943 + 14.715 - 0.829 \quad (S = \underline{38.5})$$

and our  $x$ 's are not all positive

If we increase  $t$  by 0.943 all our  $x$ 's will be positive, giving us a new  $R$

$$R = 0 + 10 + 2 \quad (S = \underline{69})$$

which is the smallest or first feasible positive value on the line of intersection. The objective function  $S$  (sphere)

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will then cut, (not tangent), the line of intersection at this point and at another point either larger all positive or some negative. For this point an objective function becomes

$$S = (2)^2 + (2)^2 + (7)^2 + 12$$

$$= 4 + 4 + 49 + 12 = 69$$

which we take as the min.

One can see from the formula for  $S$  that any positive value of  $t$  greater than 0 will give a larger value of  $S$ .  $t$  must not be larger than 2 else  $x_2$  will be negative.

Let us examine this simple system some more in detail hoping to find some facets that will be of service when dealing with

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more complex systems. We may write (2) and (3) in a more general form:

$$(1) \quad a_{11}x_1 + a_{12}x_2 + a_{13}x_3 = b_1$$

$$(2) \quad a_{21}x_1 + a_{22}x_2 + a_{23}x_3 = b_2$$

Let us suppose we have found two sets of solutions for the system above, and one can always do this by assigning values to one of the variables and solving for the other two, calling them  $(d_1, d_2, d_3)$ ,  $(\delta_1, \delta_2, \delta_3)$ . Then we have:

$$(3) \quad a_{11}d_1 + a_{12}d_2 + a_{13}d_3 = b_1$$

$$(4) \quad a_{21}d_1 + a_{22}d_2 + a_{23}d_3 = b_2$$

$$(5) \quad a_{11}\delta_1 + a_{12}\delta_2 + a_{13}\delta_3 = b_1$$

$$(6) \quad a_{21}\delta_1 + a_{22}\delta_2 + a_{23}\delta_3 = b_2$$

Comparing (3) and (5), and (4) and (6) we get:

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$$(7) \quad a \cdot p = 0$$

$$(8) \quad A \cdot p = 0$$

$$a = (a_{11}, a_{12}, a_{13})$$

$$A = (a_{21}, a_{22}, a_{23})$$

$$p = x - d$$

In other words  $p$  is orthogonal to both coefficient rows, and  $p$  also gives the direction of the line of intersection of (1) and (2). The equation of this line of intersection may be written:

$$(9) \quad r = d + t p$$

where  $t$  is a scalar multiplier.  $r$  in (9) is a solution for the system (1) and (2) for it satisfies both (1) and (2). Eqs. (7) and (8) are of far reaching consequence for they



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are true for systems of many equations and many unknowns as we shall soon show.

Let us temporarily return to our original two numerical equations:

$$2x_1 + x_2 + x_3 = 12$$

$$1x_1 + 2x_2 + 3x_3 = 26$$

one solution to this system is

$$(d_1, d_2, d_3) = (0 + 10 + 2)$$

and a second solution is

$$(r_1, r_2, r_3) = (2 + 0 + 8)$$

$$p = r - d = 2 - 10 + 6 = 2(-5 + 3)$$

$$p = 1 - 5 + 3$$

One can get this direction by taking column cofactors.

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It is better to take out any common factor in  $P$  before one finds the eq. of the line of intersection.

$$r = \alpha + t(\gamma - \alpha) = \alpha + t\rho$$

will satisfy (1) and (2) and is one solution to that system since  $\alpha$  is a solution to the system and  $(\gamma - \alpha)$  gives zero for each equation in the system.

We go to a slightly more complex system. Minimize

$$(1) \quad S = F(x_1, x_2, x_3, x_4)$$

subject to the constraints

$$(2) \quad a_{11}x_1 + a_{12}x_2 + a_{13}x_3 + a_{14}x_4 = b_1$$

$$(3) \quad a_{21}x_1 + a_{22}x_2 + a_{23}x_3 + a_{24}x_4 = b_2$$

Let  $\alpha$  and  $\gamma$  be two distinct

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Solutions for the system (2), (3)  
then we may write

$$(4) \quad A \cdot d = b_1$$

$$(5) \quad A \cdot d = b_2$$

$$(6) \quad A \cdot \gamma = b_1$$

$$(7) \quad A \cdot \gamma = b_2$$

Comparing (4) and (6); ~~and (5) and (7)~~:

$$(8) \quad A \cdot p = 0$$

$$(9) \quad A \cdot p = 0$$

$$a = (a_{11}, a_{12}, a_{13}, a_{14})$$

$$A = (a_{21}, a_{22}, a_{23}, a_{24})$$

$$p = \gamma - d$$

From (4) and (5) or (6) and (7) we get

$$(10) \quad (b_2 a - b_1 A) \cdot d = 0 \quad \text{and}$$

$$(11) \quad (b_2 a - b_1 A) \cdot \gamma = 0$$

which mean that all solutions to the system (2), and (3) lie in a plane thru the origin and perpendicular to the vector:

$$(b_2 a - b_1 A).$$

We revise our theory slightly:

Let us suppose that  $d = (d_1, \dots, d_n)$  is a solution to the system (2), (3) and that  $\gamma = (\gamma_1, \dots, \gamma_n)$  is perpendicular to both  $a$  and  $A$ , we can then write the following four equations:

$$(1) \quad a \cdot d = b_1$$

$$(2) \quad A \cdot d = b_2$$

$$(3) \quad a \cdot \gamma = 0$$

$$(4) \quad A \cdot \gamma = 0$$

$d + \gamma$  is also a solution to the system under consideration. Ex-

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Expanding the four equations we get

$$(5) \quad a_{11}d_1 + a_{12}d_2 + a_{13}d_3 + a_{14}d_4 = b_1$$

$$(6) \quad a_{21}d_1 + a_{22}d_2 + a_{23}d_3 + a_{24}d_4 = b_2$$

$$(7) \quad a_{11}\delta_1 + a_{12}\delta_2 + a_{13}\delta_3 + a_{14}\delta_4 = 0$$

$$(8) \quad a_{21}\delta_1 + a_{22}\delta_2 + a_{23}\delta_3 + a_{24}\delta_4 = 0$$

Solving (5) and (6) for  $d_3$  and  $d_4$  we get

$$(9) \quad d_3 = [L + Md_1 + Nd_2]$$

$$(10) \quad d_4 = [F + Gd_1 + Hd_2]$$

Solving (7) and (8) for  $\delta_3$  and  $\delta_4$  we get

$$(11) \quad \delta_3 = M\delta_1 + N\delta_2$$

$$(12) \quad \delta_4 = G\delta_1 + H\delta_2$$

$$(13) \quad d = d_1 + d_2 + [L + Md_1 + Nd_2] + [F + Gd_1 + Hd_2]$$

$$(14) \quad \delta = \delta_1 + \delta_2 + [M\delta_1 + N\delta_2] + [G\delta_1 + H\delta_2]$$

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$$P = (a_{13} a_{24} - a_{14} a_{23})$$

$$L = (a_{24} b_1 - a_{14} b_2) / P$$

$$M = (a_{14} a_{21} - a_{11} a_{24}) / P$$

$$N = (a_{14} a_{22} - a_{12} a_{24}) / P$$

$$F = (-a_{23} b_1 + a_{13} b_2) / P$$

$$G = (a_{11} a_{23} - a_{13} a_{21}) / P$$

$$H = (a_{12} a_{23} - a_{13} a_{22}) / P$$

We note from (13) that our solution vector  $d$  has only two unknowns in it. We are to minimize the objective function:

$$f(d_1, d_2, d_3, d_4) = f(d_1, d_2)$$

From this we have the two minimizing conditions:

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$$\partial F / \partial d_1 = 0$$

$$\partial F / \partial d_2 = 0$$

From these two eqs. we can solve for  $d_1$  and  $d_2$  and equations (9) and (10) give us, with the help of the  $d_1$  and  $d_2$  just found, the values of  $d_3$  and  $d_4$ . Our solution vector  $d = d_1 + d_2 + d_3 + d_4$  is then known and if all  $d_i$  are positive our problem is solved.

If some of the  $d_i$  are negative we must have this point along  $\delta$  in order to maintain solution to our system and to correct  $d_i$ . See eq. (14). We now correct our solution so that:

$$p = d + \delta$$

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has all positive components. The nature of the objective function  $F$  will have to play its part in this correction, unless the number of equations in our system is 1 less than the number of unknowns. To see this suppose we have a system of  $n-1$  equations in  $n$  unknowns then.

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = 0$$

$$a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = 0$$

$$\dots \dots \dots$$

$$a_{n-1,1}x_1 + a_{n-1,2}x_2 + \dots + a_{n-1,n}x_n = 0$$

One can transpose the last column on the right across the equality sign and get:

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1,n-1}x_{n-1} = -a_{1n}x_n$$

$$a_{21}x_1 + a_{22}x_2 + \dots + a_{2,n-1}x_{n-1} = -a_{2n}x_n$$

$$\dots \dots \dots$$

$$a_{n-1,1}x_1 + a_{n-1,2}x_2 + \dots + a_{n-1,n-1}x_{n-1} = -a_{n-1,n}x_n$$



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One can solve the square matrix on the left for  $\delta_1, \delta_2, \dots, \delta_{n-1}$  in terms of  $\delta_n$  and get:

$$\delta_1 = C_1 \delta_n$$

$$\delta_2 = C_2 \delta_n$$

$$\dots$$

$$\delta_{n-1} = C_{n-1} \delta_n.$$

thus:

$$\delta = \delta_n (C_1 + C_2 + \dots + C_{n-1} + 1)$$

and thus  $\delta$  has a fixed direction or  $n-1$  equations in  $n$  unknowns intersect in one line or  $n-1$  hyperplanes with  $n$  unknowns intersect in one line. The  $C_i$  are known quantities and constants. They are or are proportional, proportional to the column cofactors in order from left to right in the original system. From (14) one sees there is an indefinite number of intersections in that system. For any

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Choice of  $\delta_1$  and  $\delta_2$  one gets a definite line of intersection. From eq. (14) this choice of  $\delta_1$  and  $\delta_2$  determines the whole  $\delta$  since  $\delta_3$  and  $\delta_4$  are determined by the  $\delta_1$  and  $\delta_2$ , see eqs. (11) and (12).

Consider the system:

$$\begin{aligned} \delta_1 + 2\delta_2 + \delta_3 + \delta_4 &= 12 \\ 2\delta_1 + \delta_2 + 2\delta_3 + 3\delta_4 &= 26 \end{aligned}$$

$$F = (\delta_1 - 2)^2 + (\delta_2 - 1)^2 + (\delta_3 - 4)^2 + (\delta_4 - 3)^2 + 12$$

$$P = 1$$

$$L = 10, \quad M = -1, \quad N = -5$$

$$F = 2, \quad G = 0, \quad H = 3$$

$$\delta_3 = 10 - \delta_1 - 5\delta_2$$

$$\delta_4 = 2 + 3\delta_2$$

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$$f = (d_1 - 2)^2 + (d_2 - 1)^2 + (6 - d_1 - 5d_2)^2 + (3d_2 - 1)^2 + 12$$

$$2(d_1 - 2) - 2(6 - d_1 - 5d_2) = 0 = \partial f / \partial d_1$$

$$2(d_2 - 1) - 10(6 - d_1 - 5d_2) + 6(3d_2 - 1) = 0 = \partial f / \partial d_2 \therefore$$

$$4d_1 + 10d_2 = 16$$

$$12d_1 + 70d_2 = 68 \quad \therefore$$

$$d_1 = 11/4, \quad d_2 = 11/2$$

and

$$d_3 = 19/4, \quad d_4 = 7/2$$

putting these values into  $f$  and we get

$$f = 13 \frac{5}{8} = 13 \frac{5}{8} = 13.625 \text{ (min.)} \quad \nabla$$

To get some confirmation as to whether  $f$  is a min. we change our  $d_i$  slightly and write

$$d_1 = 3, \quad d_2 = 1/2, \quad d_3 = 5, \quad d_4 = 4 \quad \text{then}$$

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$$F_2 = (1)^2 + (1/2)^2 + (1)^2 + (1)^2 + 12 = 15.250$$

showing that  $F$  is larger for values of  $\delta_j$  slightly different from those for the min.

In this case all  $\delta_j$  are positive and they are the required answers. They satisfy the constraint equations.

We now consider the general case. Here we shall have  $m$  equations in  $N$  unknowns and we want to minimize a function  $F(x_1, \dots, x_n)$  subject to the  $m$  equations of constraint. we write: minimize

$$(1) \quad F(x_1, \dots, x_n)$$

subject to:

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$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n-1}x_{n-1} + a_{1n}x_n = b_1$$

$$a_{21}x_1 + a_{22}x_2 + \dots + a_{2n-1}x_{n-1} + a_{2n}x_n = b_2$$

(2)

$$a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn-1}x_{n-1} + a_{mn}x_n = b_m$$

$$n > m$$

Eq. (2) may be written:

$$a_{1, n-m+1}x_{n-m+1} + \dots + a_{1n}x_n = b_1 - a_{11}x_1 - a_{12}x_2 - \dots - a_{1, n-m}x_{n-m}$$

$$a_{2, n-m+1}x_{n-m+1} + \dots + a_{2n}x_n = b_2 - a_{21}x_1 - a_{22}x_2 - \dots - a_{2, n-m}x_{n-m}$$

(3)

$$a_{m, n-m+1}x_{n-m+1} + \dots + a_{mn}x_n = b_m - a_{m1}x_1 - a_{m2}x_2 - \dots - a_{m, n-m}x_{n-m}$$

The  $m$  by  $m$  matrix on the left of (3) can be solved for the  $x_{n-m+1}$  to  $x_n$  in terms of the right side of eq. (2) getting

$$x_{n-m+1} = M_0 + M_1x_1 + M_2x_2 + \dots + M_{n-m}x_{n-m}$$

(4)

$$x_n = Q_0 + Q_1x_1 + Q_2x_2 + \dots + Q_{n-m}x_{n-m}$$

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These values in (4) are put into  $f$  and we get:

$$(5) \quad f(x_1, \dots, x_n) = f(x_1, \dots, x_{n-m})$$

One then forms the set of eqs.:

$$\partial f(x_1, \dots, x_{n-m}) / \partial x_1 = 0$$

$$(6) \quad \partial f(x_1, \dots, x_{n-m}) / \partial x_2 = 0$$

$$\dots \dots \dots$$

$$\partial f(x_1, \dots, x_{n-m}) / \partial x_{n-m} = 0$$

The system in (6) can be solved for  $x_1, \dots, x_{n-m}$ . Eq. (4) then, with these values set in, gives us the remaining values of  $r$ , where

$$r = x_1 + x_2 + \dots + x_n.$$

$r$  is the minimizing vector.  $r_{\min}$

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Corresponding to simply omit the letters with zero subscripts in eq. (4).

With this generalization we are now in a position to discuss chemical reactions and the synthesis of desired chemical compounds, under various conditions (constraints of temp. pressure, concentration etc).

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It ought to be emphasized that one gets the coefficients of the various  $\delta$  as a by-product in calculating the  $\delta$  relation and they do not have to be calculated separately. This is quite a saving of time and effort. Keep this in mind.

In anticipation of a chemical problem of the same order we do the constraints calculation for a system of three equations in ten unknowns, the objective

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function being specified later, after looking up some quantities in published tables. we write:

$$(1) \quad \begin{aligned} a_{11} X_1 + a_{12} X_2 + \dots + a_{110} X_{10} &= b_1 \\ a_{21} X_1 + a_{22} X_2 + \dots + a_{210} X_{10} &= b_2 \\ a_{31} X_1 + a_{32} X_2 + \dots + a_{310} X_{10} &= b_3 \end{aligned}$$

This may be written:

$$\begin{aligned} a_{18} X_8 + a_{19} X_9 + a_{110} X_{10} &= b_1 - a_{11} X_1 - \dots - a_{17} X_7 \\ a_{28} X_8 + a_{29} X_9 + a_{210} X_{10} &= b_2 - a_{21} X_1 - \dots - a_{27} X_7 \\ a_{38} X_8 + a_{39} X_9 + a_{310} X_{10} &= b_3 - a_{31} X_1 - \dots - a_{37} X_7 \end{aligned}$$

$$\begin{array}{c} \left| \begin{array}{c} X_8 \\ X_9 \\ X_{10} \end{array} \right| = \underbrace{\left| \begin{array}{ccc} L_1 & M_1 & N_1 \\ L_2 & M_2 & N_2 \\ L_3 & M_3 & N_3 \end{array} \right|}_{P} \left| \begin{array}{c} b_1 - a_{11} X_1 - \dots - a_{17} X_7 \\ b_2 - a_{21} X_1 - \dots - a_{27} X_7 \\ b_3 - a_{31} X_1 - \dots - a_{37} X_7 \end{array} \right| \end{array}$$

$$X_8 = F_0 + F_1 X_1 + \dots + F_7 X_7$$

$$X_9 = G_0 + G_1 X_1 + \dots + G_7 X_7$$

$$X_{10} = H_0 + H_1 X_1 + \dots + H_7 X_7$$



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$$L_1 = \begin{vmatrix} a_{29} & a_{210} \\ a_{39} & a_{310} \end{vmatrix}$$

$$M_1 = - \begin{vmatrix} a_{19} & a_{110} \\ a_{39} & a_{310} \end{vmatrix}$$

$$L_2 = - \begin{vmatrix} a_{28} & a_{210} \\ a_{38} & a_{310} \end{vmatrix}$$

$$M_2 = \begin{vmatrix} a_{18} & a_{110} \\ a_{38} & a_{310} \end{vmatrix}$$

$$L_3 = \begin{vmatrix} a_{28} & a_{29} \\ a_{38} & a_{39} \end{vmatrix}$$

$$M_3 = - \begin{vmatrix} a_{18} & a_{19} \\ a_{38} & a_{39} \end{vmatrix}$$

$$N_1 = \begin{vmatrix} a_{19} & a_{110} \\ a_{29} & a_{210} \end{vmatrix}$$

$$N_2 = - \begin{vmatrix} a_{18} & a_{110} \\ a_{28} & a_{210} \end{vmatrix}$$

$$N_3 = \begin{vmatrix} a_{18} & a_{19} \\ a_{28} & a_{29} \end{vmatrix}$$

$$P = \begin{vmatrix} a_{18} & a_{19} & a_{110} \\ a_{28} & a_{29} & a_{210} \\ a_{38} & a_{39} & a_{310} \end{vmatrix}$$

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$$F_0 = (L_1 b_1 + M_1 b_2 + N_1 b_3) / P$$

$$F_1 = -(L_1 a_{11} + M_1 a_{21} + N_1 a_{31}) / P$$

$$F_2 = -(L_1 a_{12} + M_1 a_{22} + N_1 a_{32}) / P$$

$$F_3 = -(L_1 a_{13} + M_1 a_{23} + N_1 a_{33}) / P$$

$$F_4 = -(L_1 a_{14} + M_1 a_{24} + N_1 a_{34}) / P$$

$$F_5 = -(L_1 a_{15} + M_1 a_{25} + N_1 a_{35}) / P$$

$$F_6 = -(L_1 a_{16} + M_1 a_{26} + N_1 a_{36}) / P$$

$$F_7 = -(L_1 a_{17} + M_1 a_{27} + N_1 a_{37}) / P$$

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$$G_0 = (L_2 b_1 + M_2 b_2 + N_2 b_3) / P$$

$$G_1 = -(L_2 a_{11} + M_2 a_{21} + N_2 a_{31}) / P$$

$$G_2 = -(L_2 a_{12} + M_2 a_{22} + N_2 a_{32}) / P$$

$$G_3 = -(L_2 a_{13} + M_2 a_{23} + N_2 a_{33}) / P$$

$$G_4 = -(L_2 a_{14} + M_2 a_{24} + N_2 a_{34}) / P$$

$$G_5 = -(L_2 a_{15} + M_2 a_{25} + N_2 a_{35}) / P$$

$$G_6 = -(L_2 a_{16} + M_2 a_{26} + N_2 a_{36}) / P$$

$$G_7 = -(L_2 a_{17} + M_2 a_{27} + N_2 a_{37}) / P$$

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$$H_0 = (L_3 b_1 + M_3 b_2 + N_3 b_3) / P$$

$$H_1 = -(L_3 a_{11} + M_3 a_{21} + N_3 a_{31}) / P$$

$$H_2 = -(L_3 a_{12} + M_3 a_{22} + N_3 a_{32}) / P$$

$$H_3 = -(L_3 a_{13} + M_3 a_{23} + N_3 a_{33}) / P$$

$$H_4 = -(L_3 a_{14} + M_3 a_{24} + N_3 a_{34}) / P$$

$$H_5 = -(L_3 a_{15} + M_3 a_{25} + N_3 a_{35}) / P$$

$$H_6 = -(L_3 a_{16} + M_3 a_{26} + N_3 a_{36}) / P$$

$$H_7 = -(L_3 a_{17} + M_3 a_{27} + N_3 a_{37}) / P$$

Our objective function is

$$F(x_1, \dots, x_{10}) = F(x_1, \dots, x_7)$$

One will then have seven equations of the type:

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$$\partial F / \partial x_j = 0$$

from which to solve for  $x_1, \dots, x_n$ .

We know what  $x_8, x_9, \text{ and } x_{10}$  are in terms of these thus are known the min. vector  $R$ :

$$R = (x_1, \dots, x_{10})$$

The  $\delta$  coefficients are the  $F, G, \text{ and } H$  coefficients with  $F_0, G_0, \text{ and } H_0$  omitted. We shall presently do a numerical example.